

Assimilation of the SCATSAR-SWI with SURFEX: Impact of local observation errors*

Jasmin Vural¹, Stefan Schneider¹, Alexander Gruber²,
Bernhard Bauer-Marschallinger³, Klaus Haslinger¹

¹Zentralanstalt für Meteorologie und Geodynamik; Vienna, Austria

²Department of Earth and Environmental Sciences, KU Leuven; Belgium

³Department of Geodesy and Geoinformation, TU Wien; Vienna, Austria

*Research project EHRSONA funded by a EUMETSAT fellowship

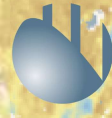


ZAMG
Zentralanstalt für
Meteorologie und
Geodynamik



LACE-DAWD

Prague, 19.09.2019



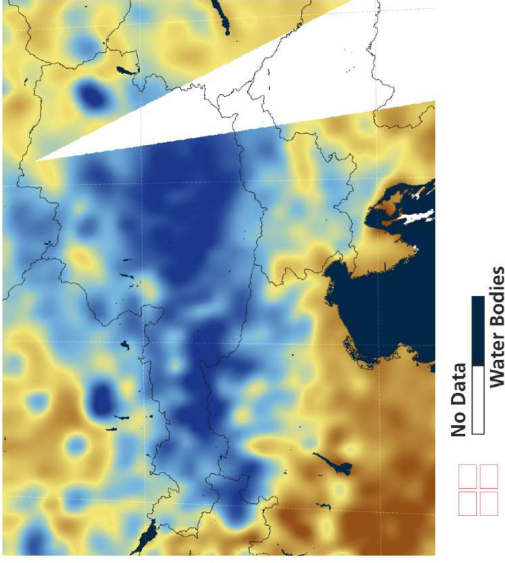
EUMETSAT

Introduction

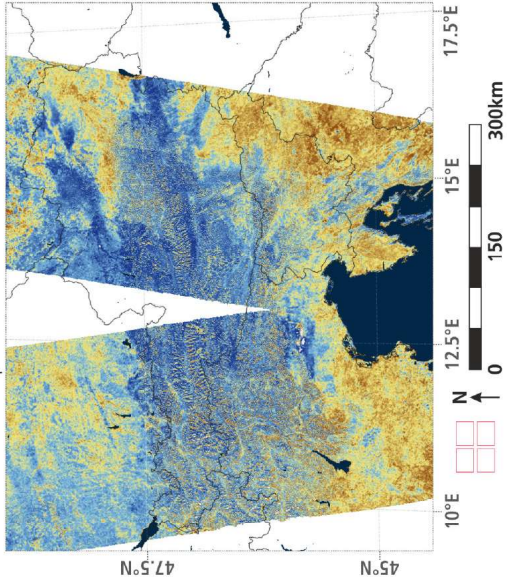
- Constant (“global”) observation error for whole domain in data assimilation with SURFEX:
e.g. $XERRROBS_M = 0.2$
- Approach:
estimate observation error for each grid point (“local”)
⇒ **Triple Collocation Analysis** (*Stoffelen 1998*)

Observations: SCATSAR-SWI

a) 25km ASCAT SSM | Evening Coverage
MetOp-A ASCAT | 2017 07 23

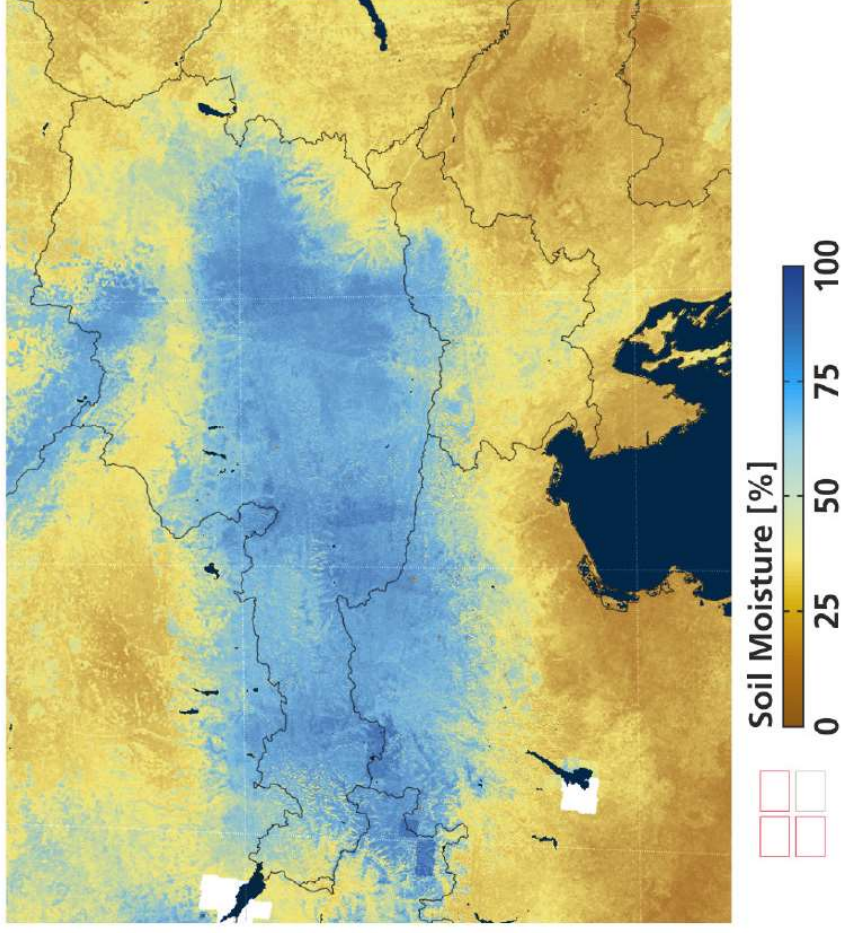


b) 1km Sentinel-1 SSM | Full Day Coverage
Sentinel-1A+B | 2017 07 23



© Bauer-Marschallinger et al. 2018

c) 1km SCATSAR-SWI | T=5 | Daily Coverage
Sentinel-1A+B & MetOp-A+B ASCAT | 2017 07 24



- temporal resolution: 1 day
- spatial resolution: 1 km
- vertical resolution: 8 layers

provided freely via the Copernicus Global Land Service

Triple Collocation Analysis

- Linear error model

$$\Theta_{\text{meas}} = \alpha + \beta\Theta_{\text{true}} + \epsilon$$
$$\Rightarrow \sigma_{\epsilon}^2$$

Triple Collocation Analysis

- Linear error model

$$\Theta_{\text{meas}} = \alpha + \beta \Theta_{\text{true}} + \epsilon$$

$\Rightarrow \sigma_{\epsilon}^2$

\Rightarrow Kalman gain

$$\mathbf{K} = \mathbf{B}\mathbf{H}^T (\mathbf{H}\mathbf{B}\mathbf{H}^T + \mathbf{R})^{-1}$$

Triple Collocation Analysis

- Linear error model

$$\Theta_{\text{meas}} = \alpha + \beta \Theta_{\text{true}} + \epsilon$$

$\Rightarrow \sigma_{\epsilon}^2$

\Rightarrow Kalman gain

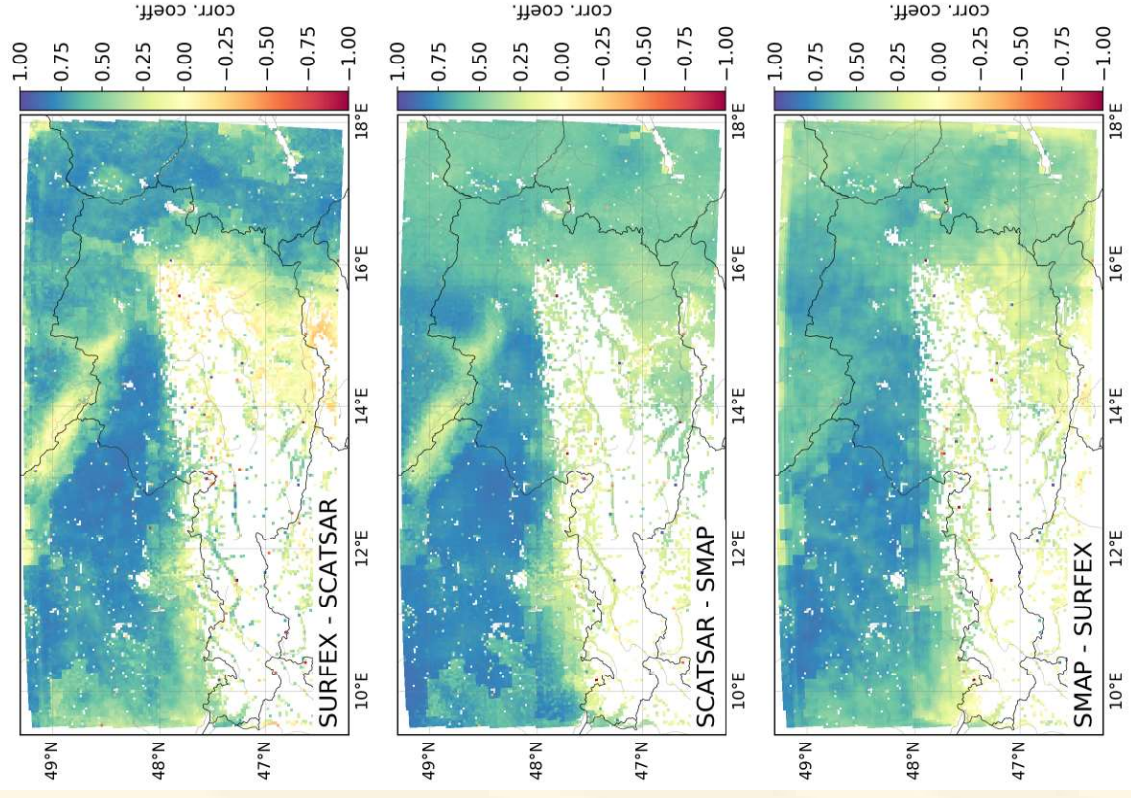
$$\mathbf{K} = \mathbf{B}\mathbf{H}^T(\mathbf{H}\mathbf{B}\mathbf{H}^T + \mathbf{R})^{-1}$$

- Data sets (zero error cross-correlation!):
 - ▷ active sensor: SCATSAR-SWI
 - ▷ passive sensor: SMAP (L3, 9 km)
 - ▷ model: SURFEX

Triple Collocation Analysis – Correlation

soil level 1

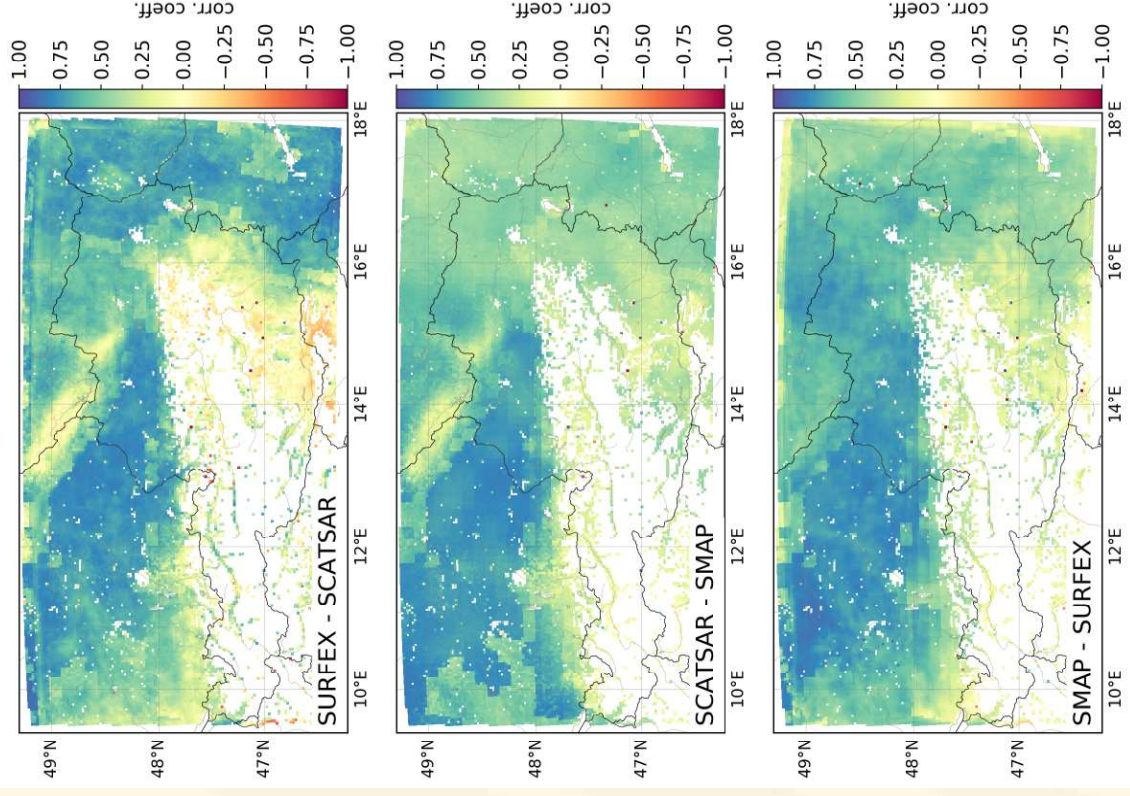
- Correlation SURFEX-SCATSAR:
 - ▷ worse with increasing depth for hills
 - ▷ better for flatlands
- Correlation with SMAP (single layer):
 - ▷ worse with increasing depth



Triple Collocation Analysis – Correlation

soil level 2

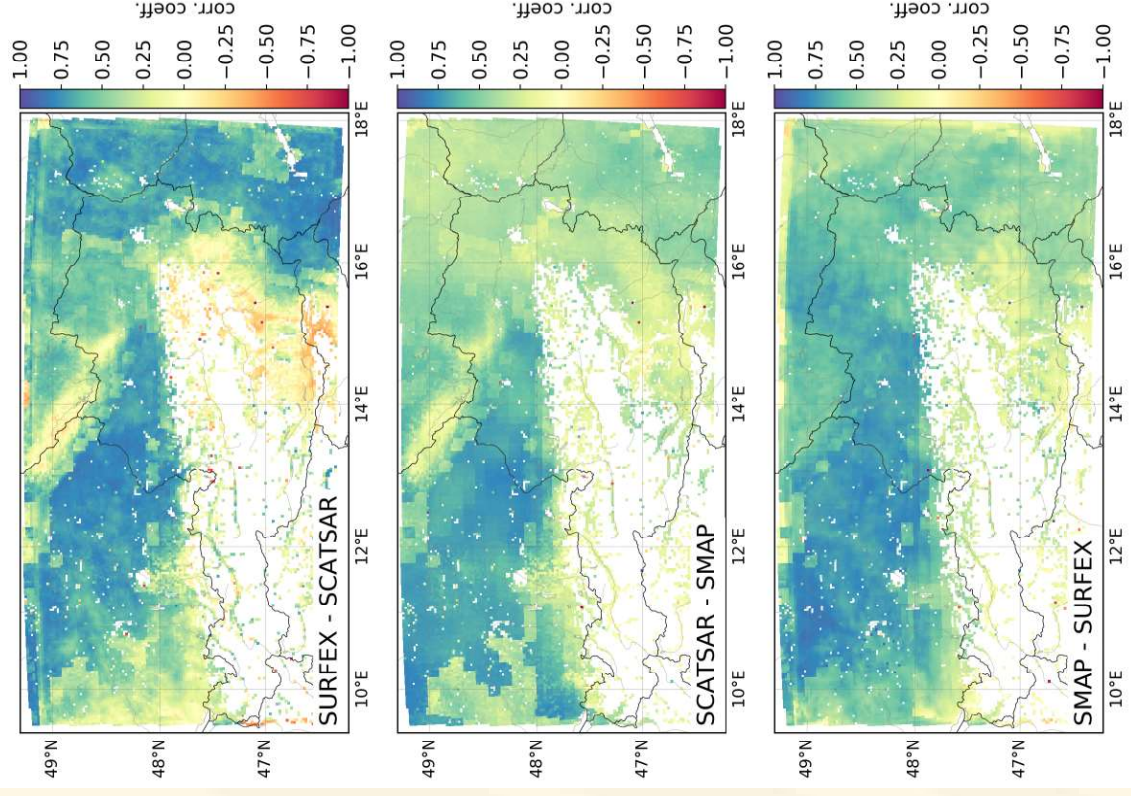
- Correlation SURFEX-SCATSAR:
 - ▷ worse with increasing depth for hills
 - ▷ better for flatlands
- Correlation with SMAP (single layer):
 - ▷ worse with increasing depth



Triple Collocation Analysis – Correlation

soil level 3

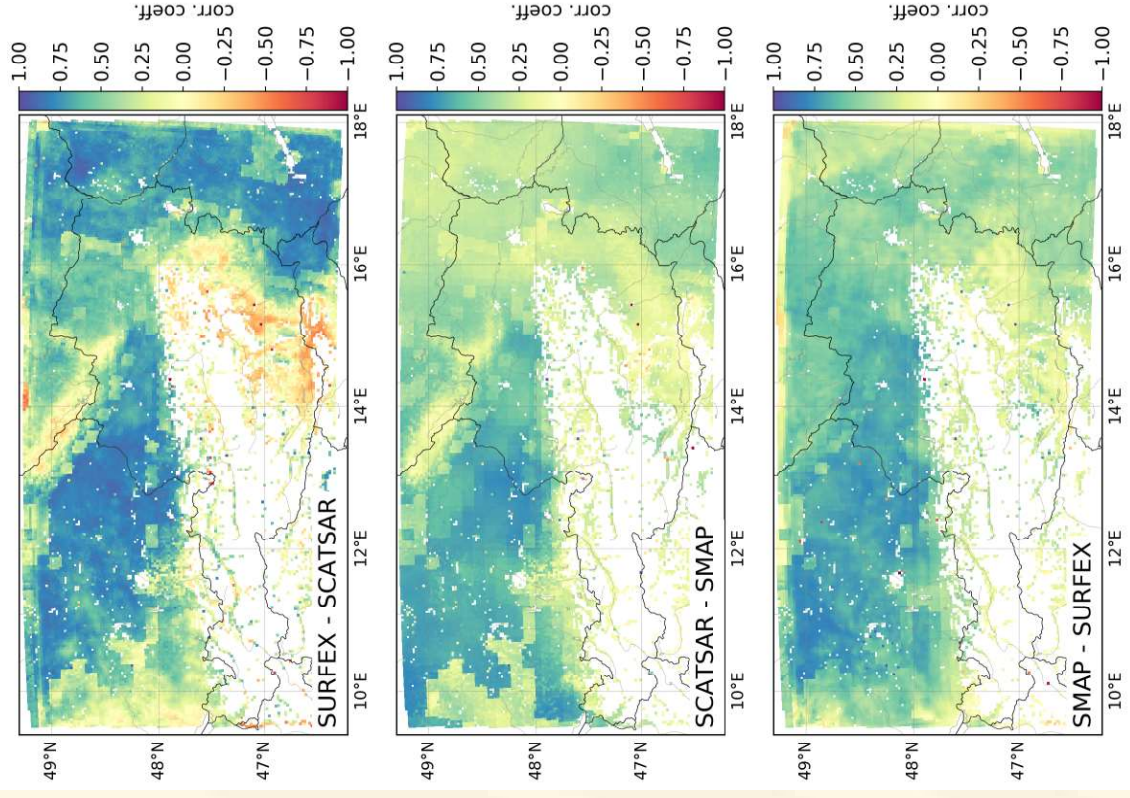
- Correlation SURFEX-SCATSAR:
 - ▷ worse with increasing depth for hills
 - ▷ better for flatlands
- Correlation with SMAP (single layer):
 - ▷ worse with increasing depth



Triple Collocation Analysis – Correlation

soil level 4

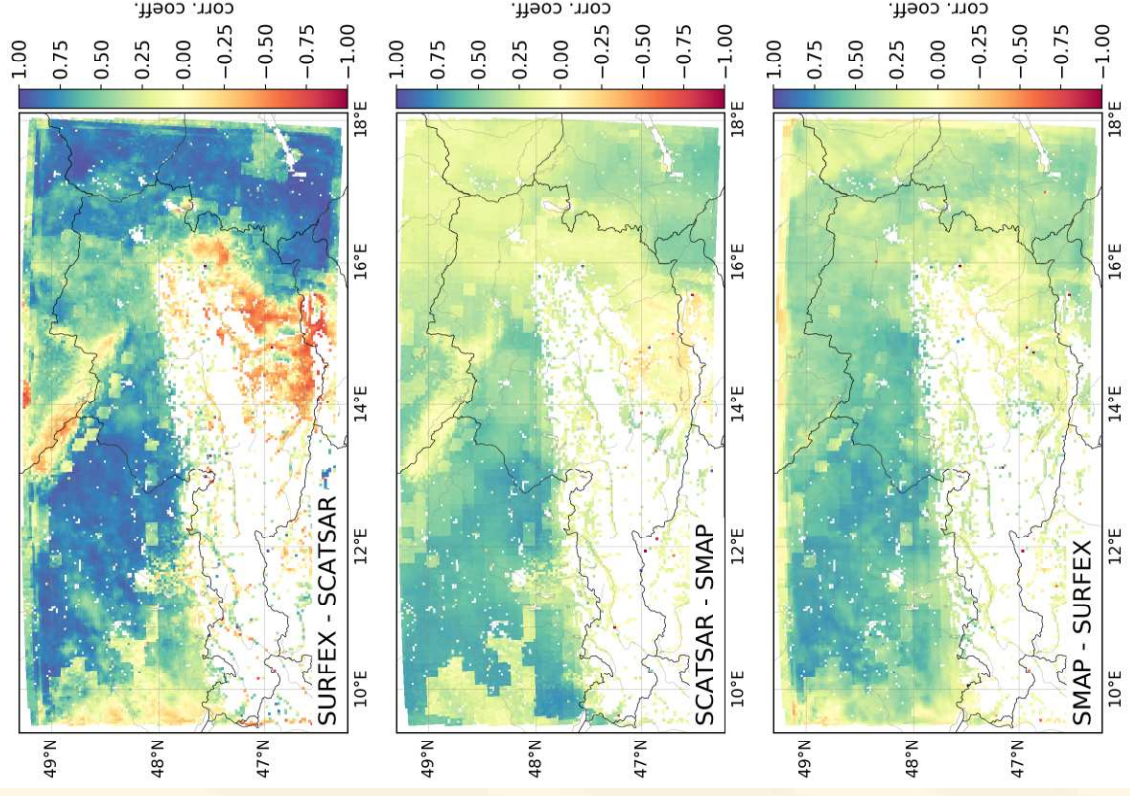
- Correlation SURFEX-SCATSAR:
 - ▷ worse with increasing depth for hills
 - ▷ better for flatlands
- Correlation with SMAP (single layer):
 - ▷ worse with increasing depth



Triple Collocation Analysis – Correlation

soil level 5

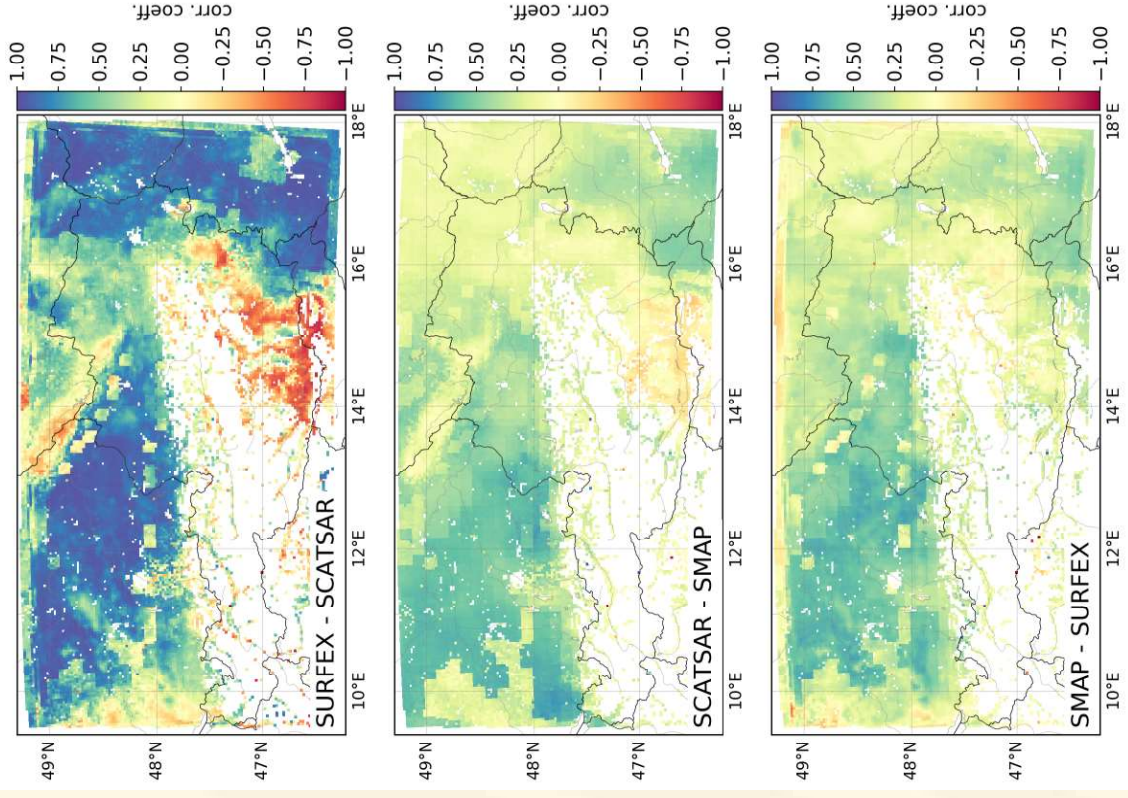
- Correlation SURFEX-SCATSAR:
 - ▷ worse with increasing depth for hills
 - ▷ better for flatlands
- Correlation with SMAP (single layer):
 - ▷ worse with increasing depth



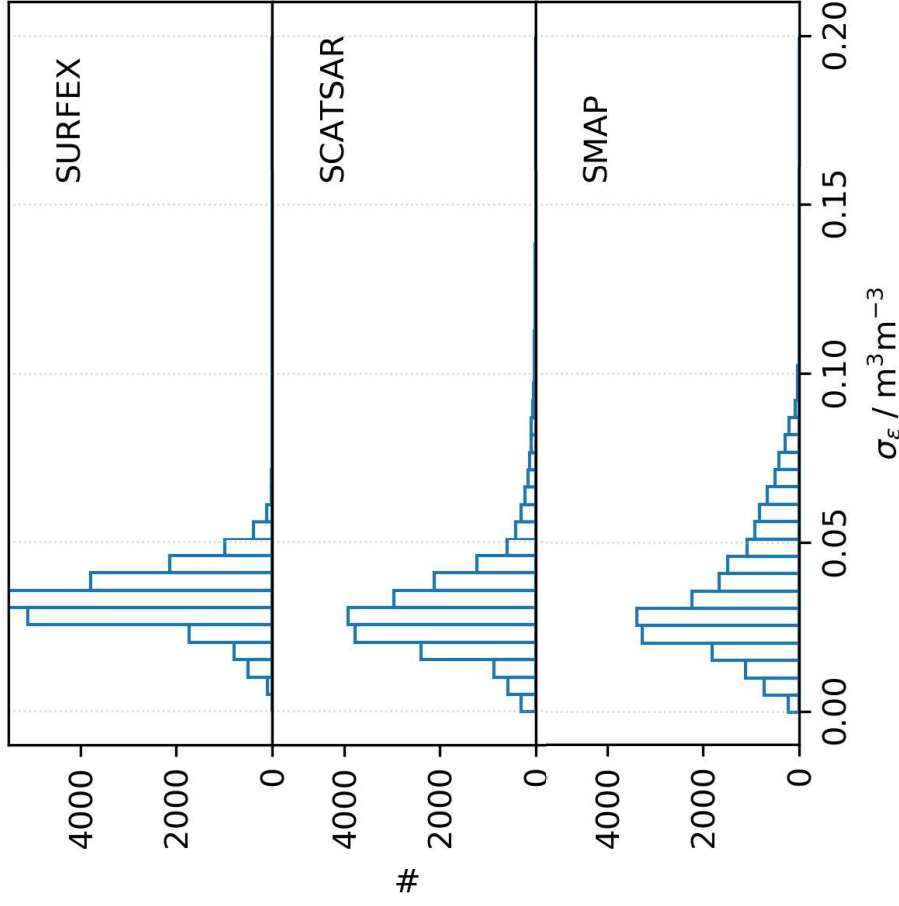
Triple Collocation Analysis – Correlation

soil level 6

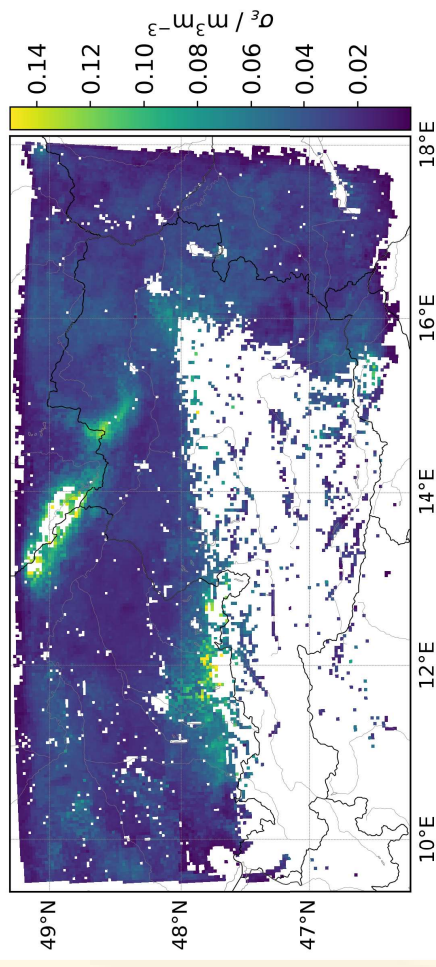
- Correlation SURFEX-SCATSAR:
 - ▷ worse with increasing depth for hills
 - ▷ better for flatlands
- Correlation with SMAP (single layer):
 - ▷ worse with increasing depth



Triple Collocation Analysis – SCATSAR error STD

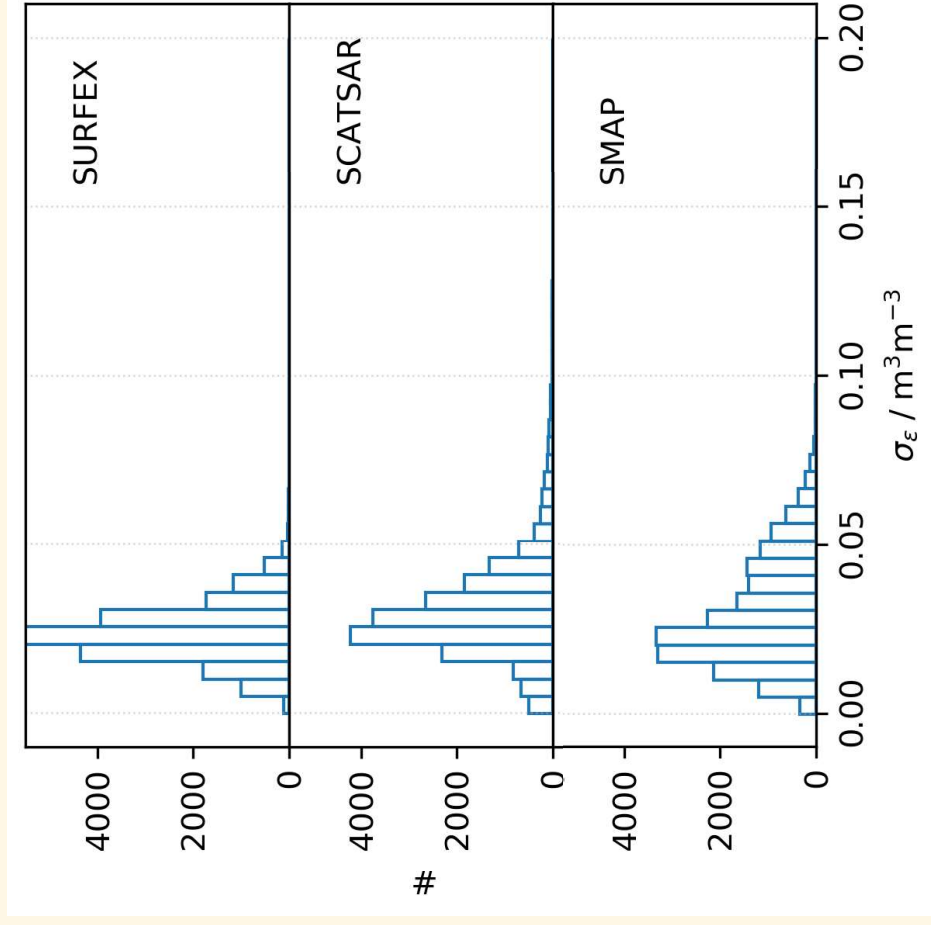


soil level 1

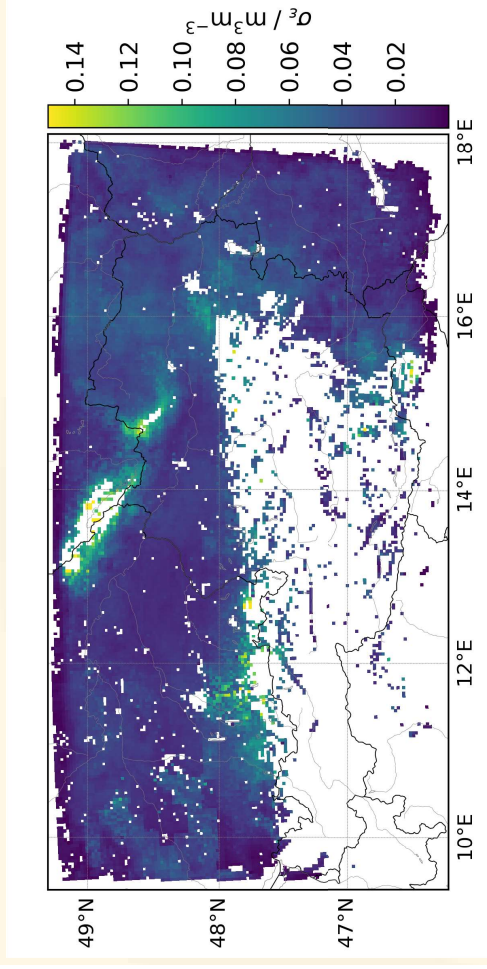


- SURFEX & SCATSAR error STD smaller with depth \Leftarrow smoother deeper levels
- SMAP error STD larger with increasing depth \Leftarrow lack of representativeness

Triple Collocation Analysis – SCATSAR error STD

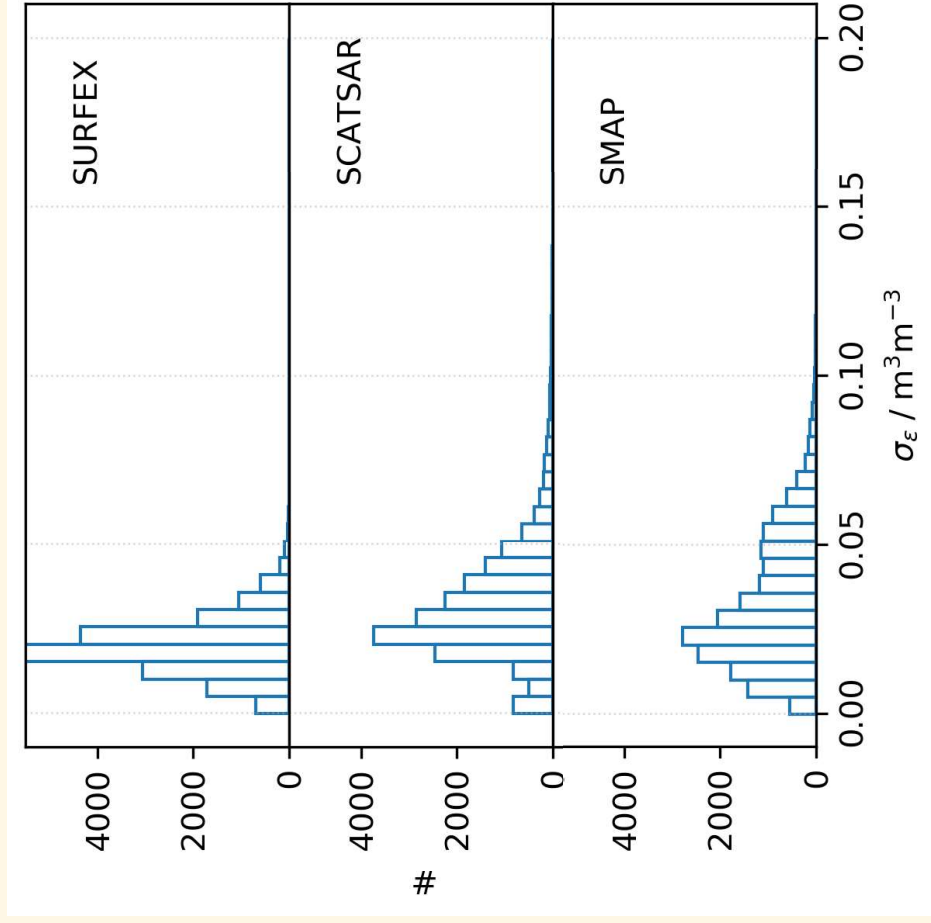


soil level 2

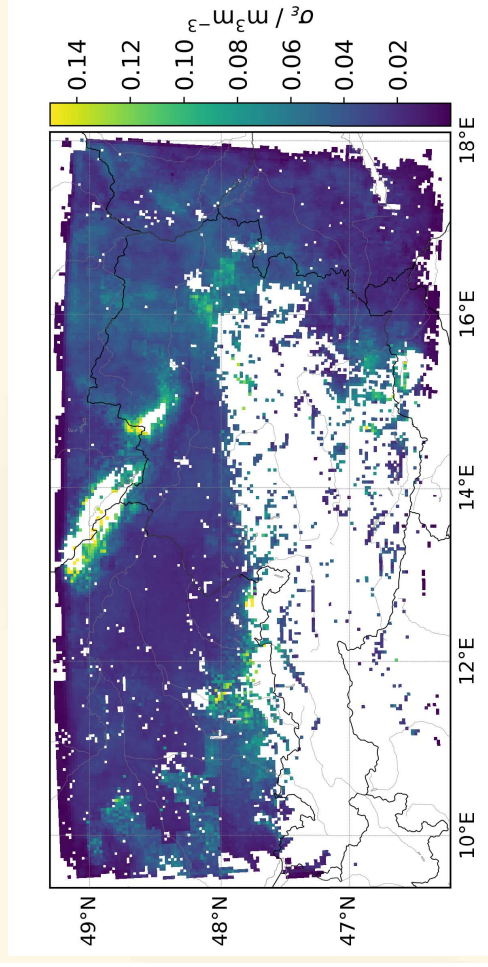


- SURFEX & SCATSAR error STD smaller with depth \Leftarrow smoother deeper levels
- SMAP error STD larger with increasing depth \Leftarrow lack of representativeness

Triple Collocation Analysis – SCATSAR error STD

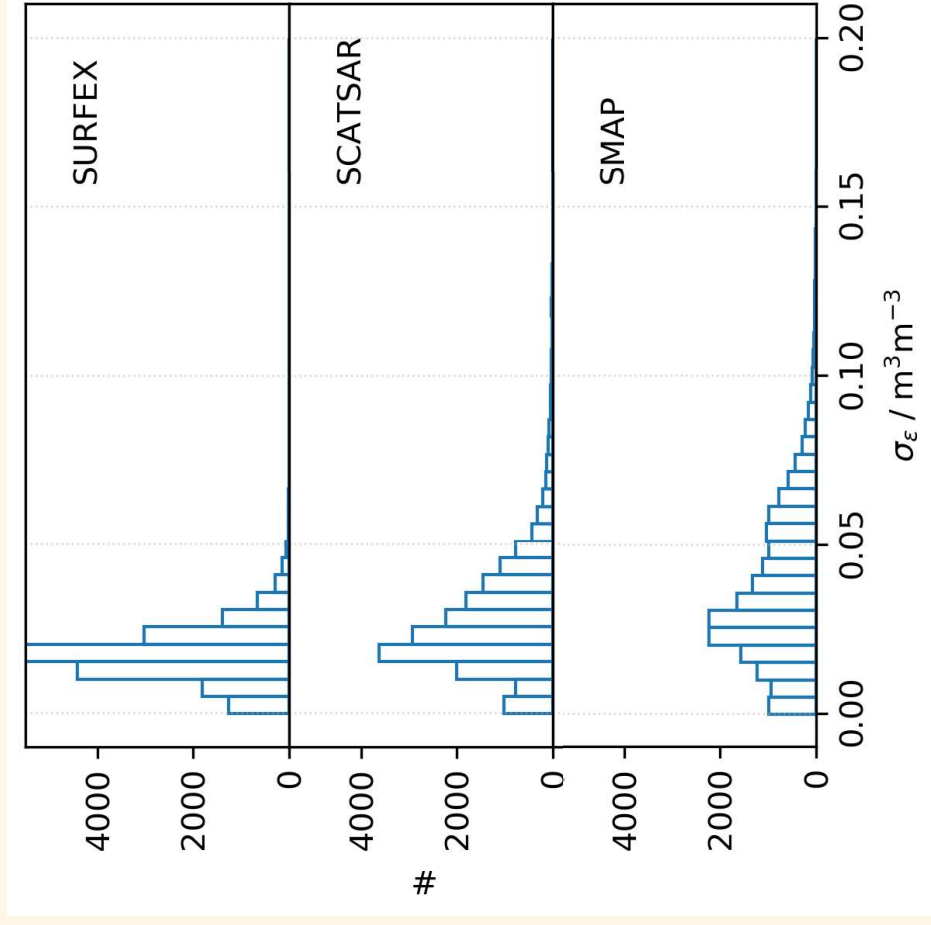


soil level 3

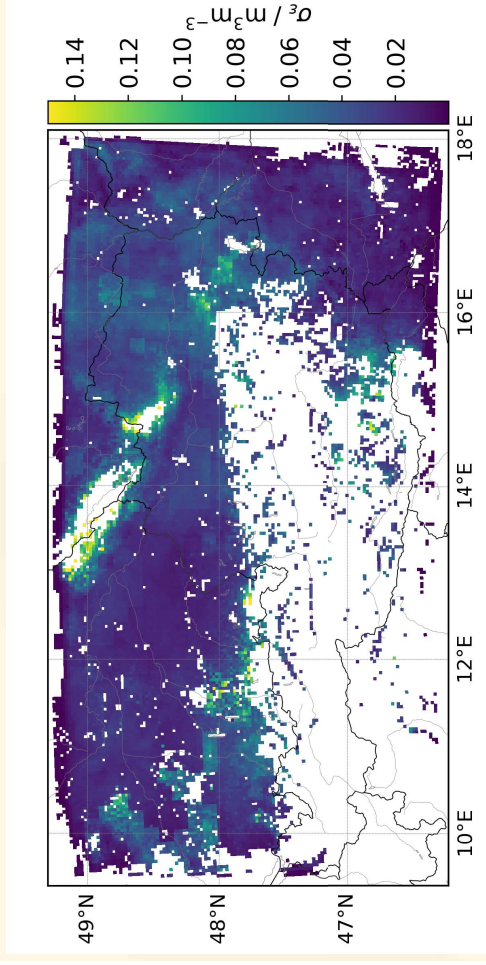


- SURFEX & SCATSAR error STD smaller with depth \Leftarrow smoother deeper levels
- SMAP error STD larger with increasing depth \Leftarrow lack of representativeness

Triple Collocation Analysis – SCATSAR error STD

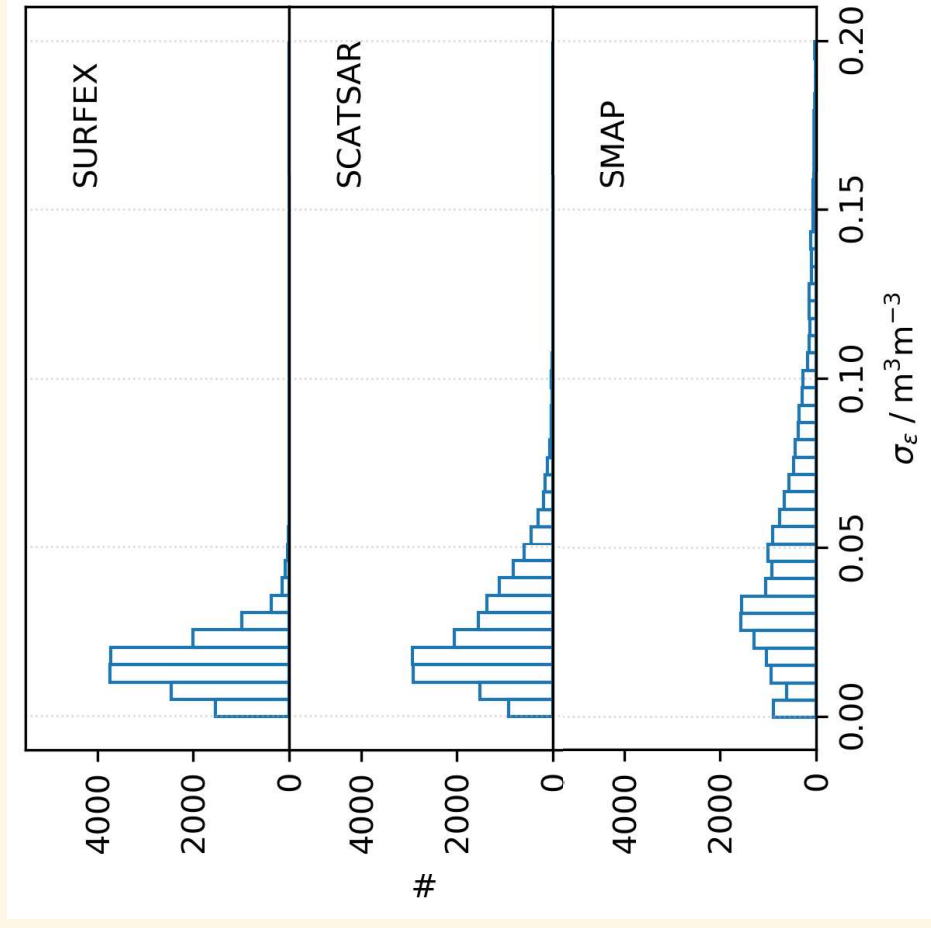


soil level 4

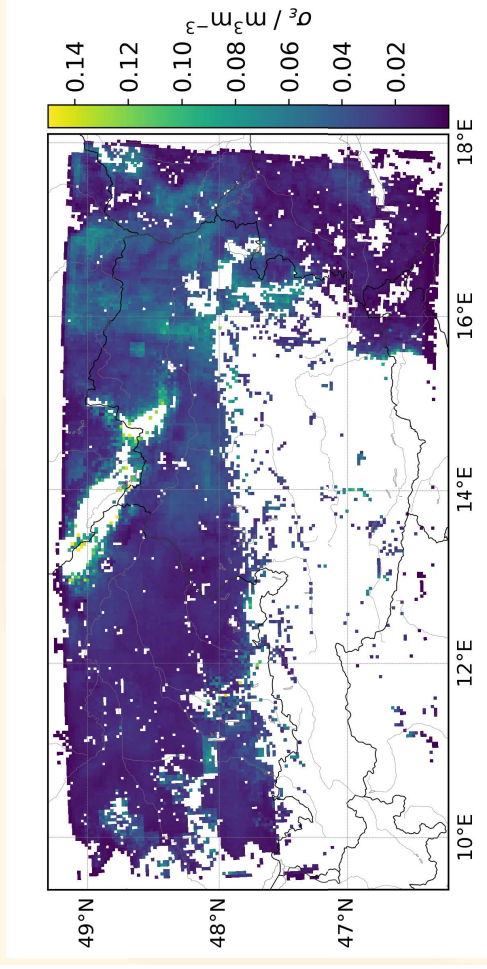


- SURFEX & SCATSAR error STD smaller with depth \Leftarrow smoother deeper levels
- SMAP error STD larger with increasing depth \Leftarrow lack of representativeness

Triple Collocation Analysis – SCATSAR error STD

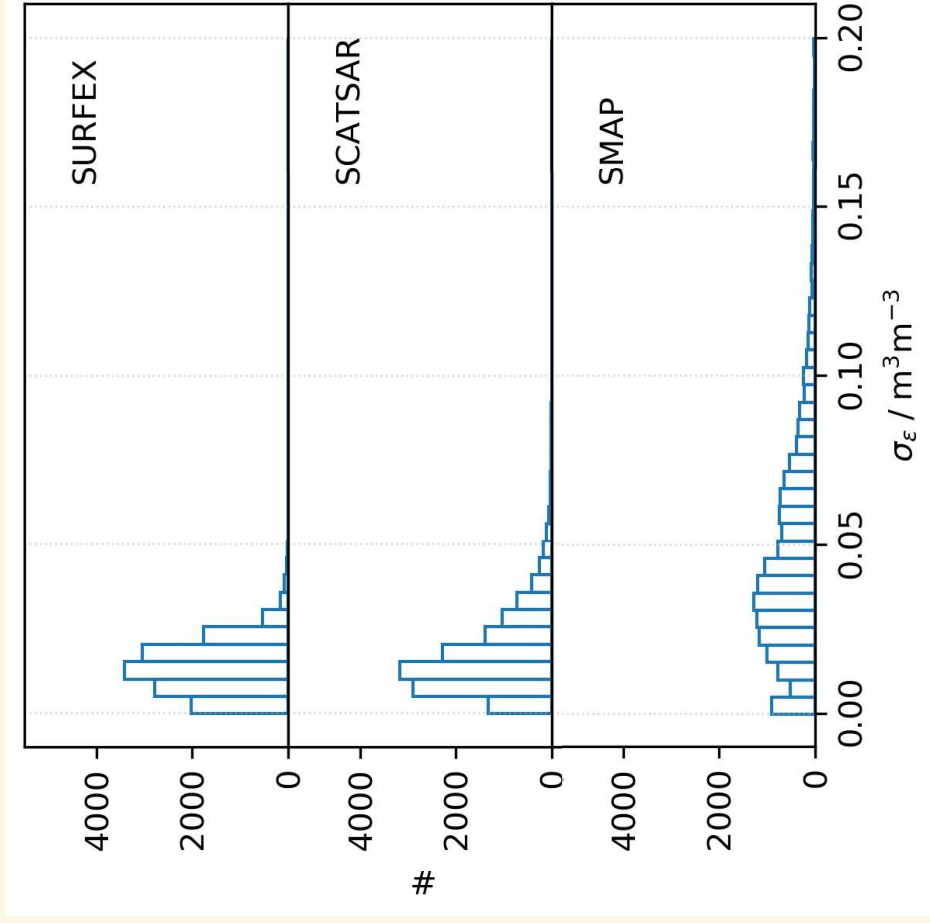


soil level 5

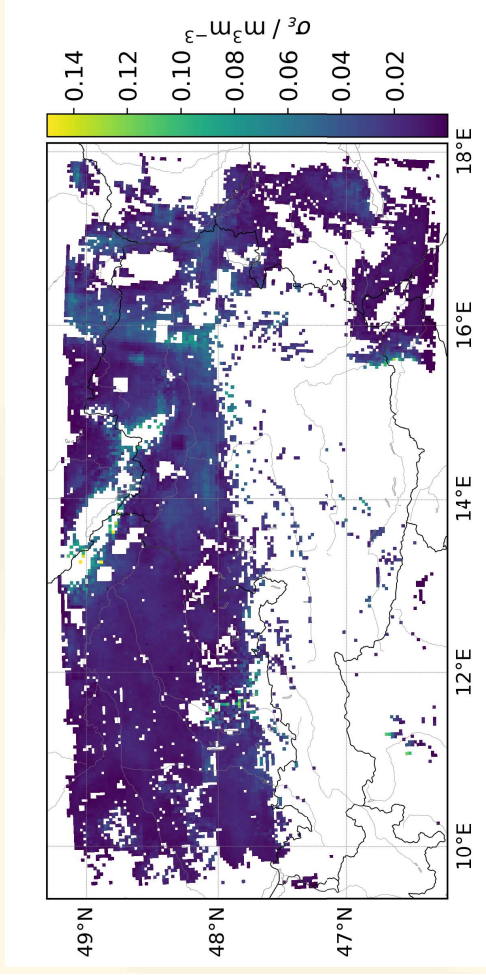


- SURFEX & SCATSAR error STD smaller with depth \Leftarrow smoother deeper levels
- SMAP error STD larger with increasing depth \Leftarrow lack of representativeness

Triple Collocation Analysis – SCATSAR error STD



soil level 6



- SURFEX & SCATSAR error STD smaller with depth \Leftarrow smoother deeper levels
- SMAP error STD larger with increasing depth \Leftarrow lack of representativeness

The data assimilation system

MODEL

- AROME CY40T1 + SURFEX 7.3
- 2.5 km grid, 90 layers

SURFEX

- version 8.1
- sEKF
- LBFIXED removed, LBEV is enough
- LERROBS = True for local observation errors

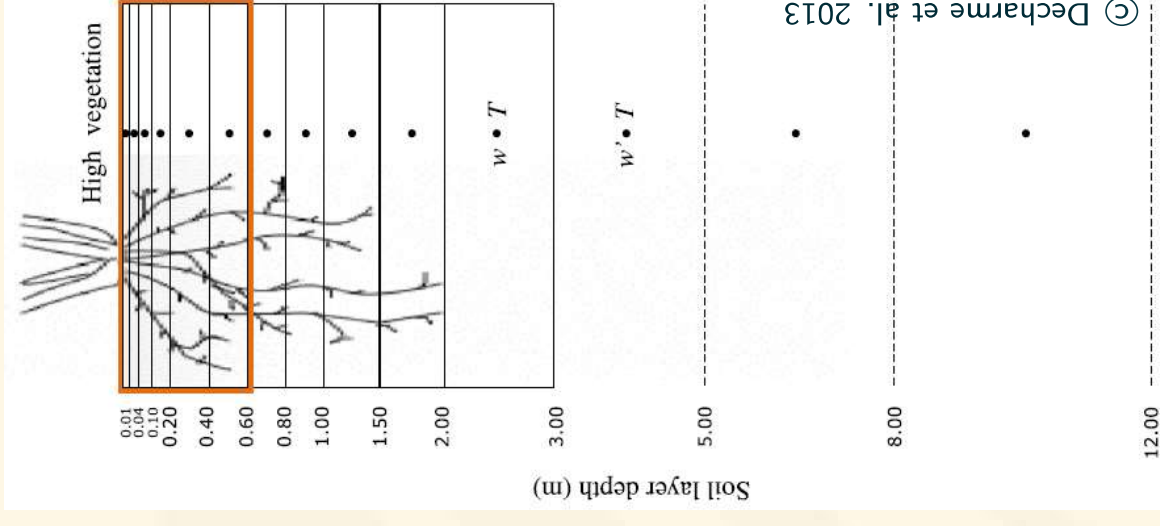
The data assimilation system

MODEL

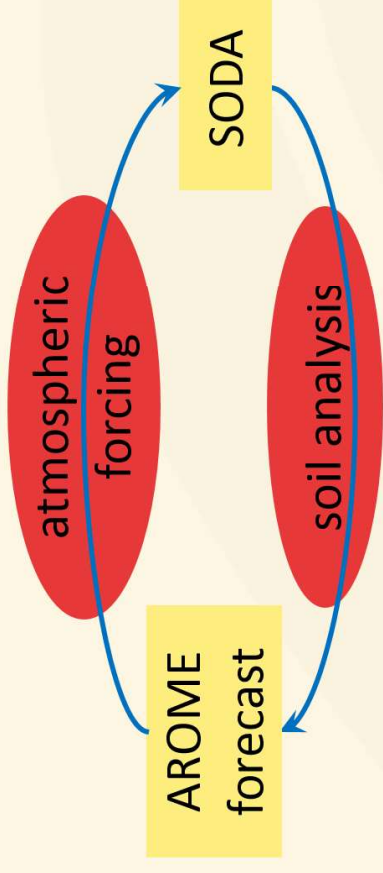
- AROME CY40T1 + SURFEX 7.3
- 2.5 km grid, 90 layers

SURFEX

- version 8.1
- sEKF
- LBFIXED removed, LBEV is enough
- LERROBS = True for local observation errors
- CISBA = 'DIF', 14 soil layers
- NOBSTYPE = 6, NVAR = 6 (WG1-6)

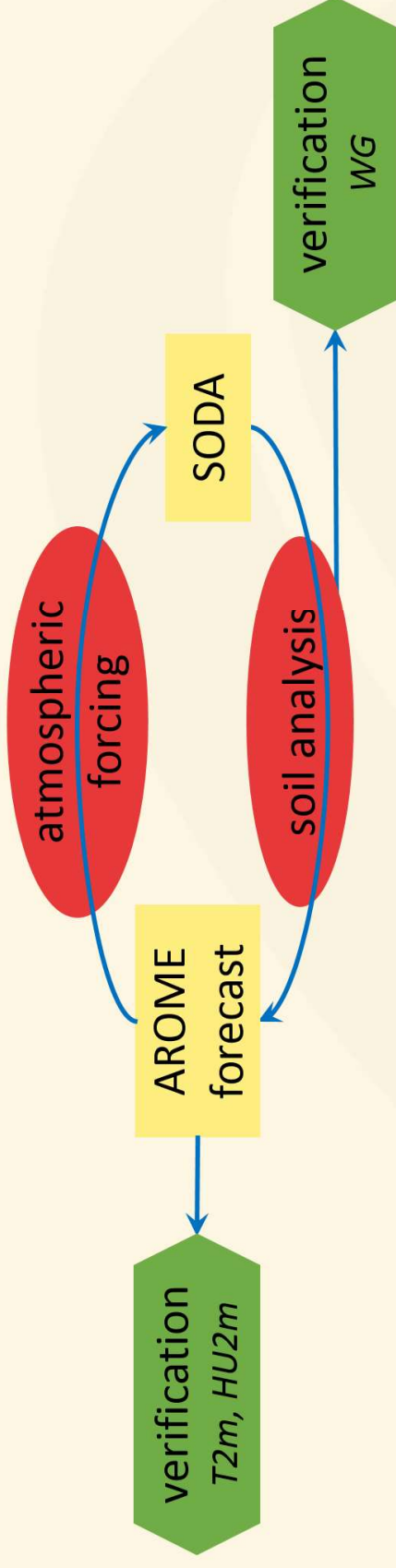


The data assimilation system



- April to September 2018
- Austrian domain
- Global vs. local observation error

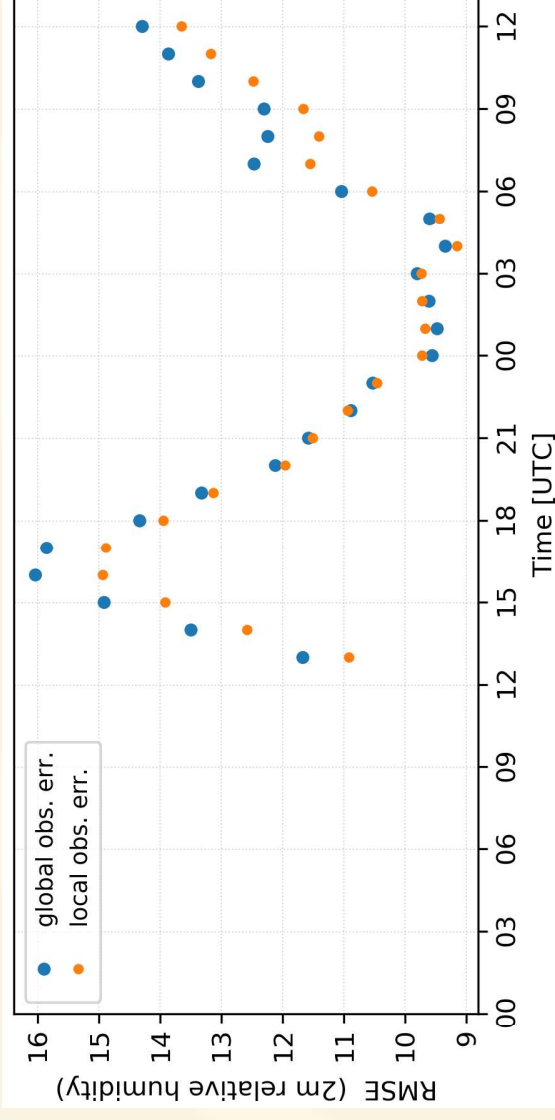
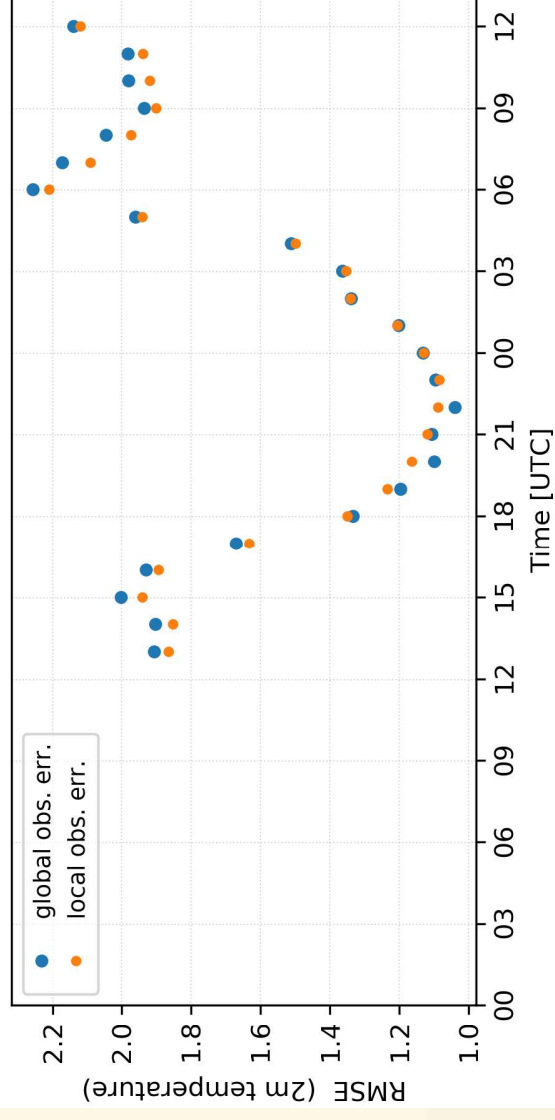
The data assimilation system



- April to September 2018
- Austrian domain
- Global vs. local observation error

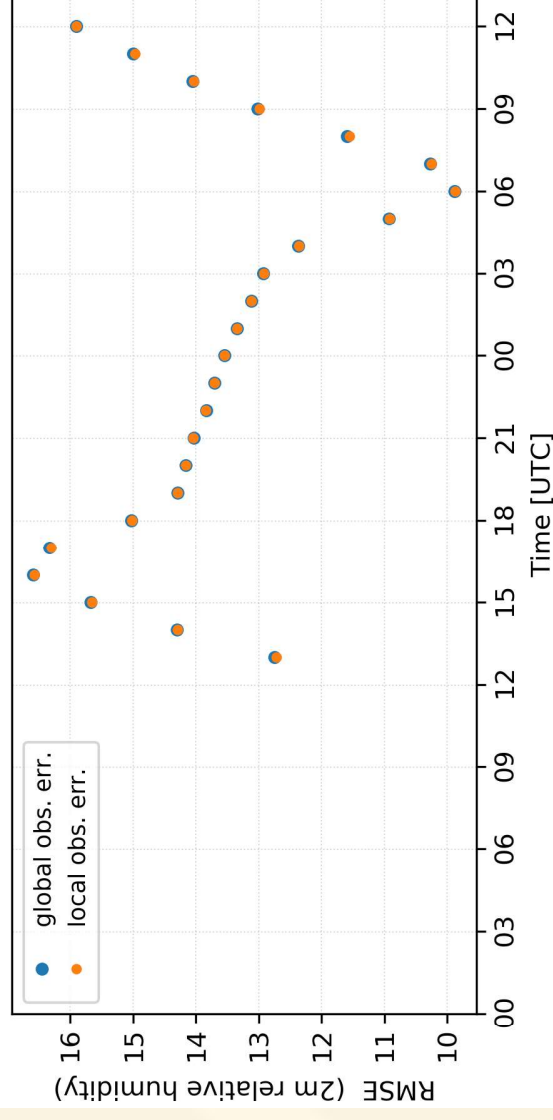
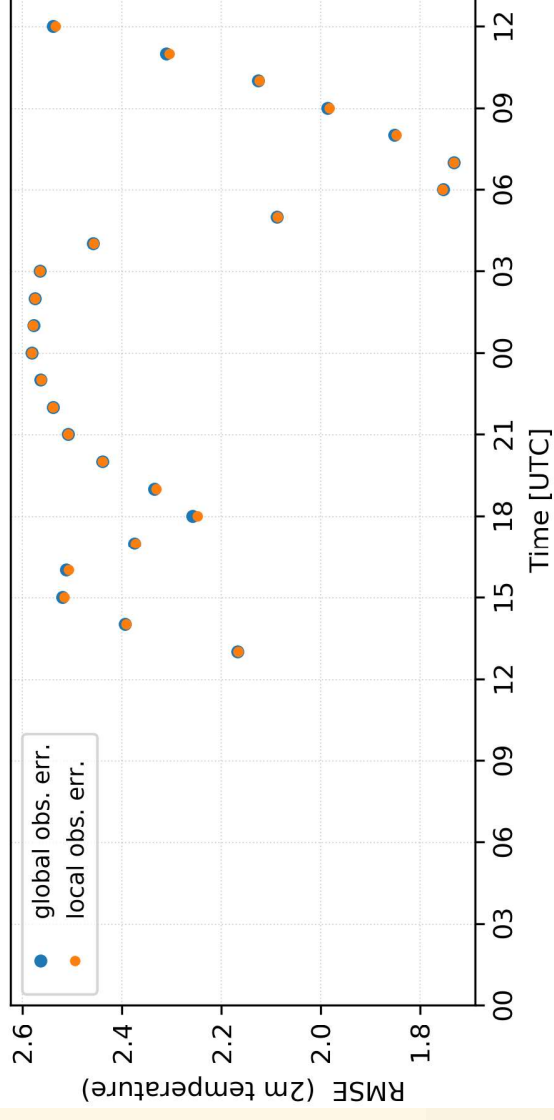
Comparison of T_{2m} & HU_{2m} with Austrian TAWES stations

- Bias & RMSE improve for some stations ...



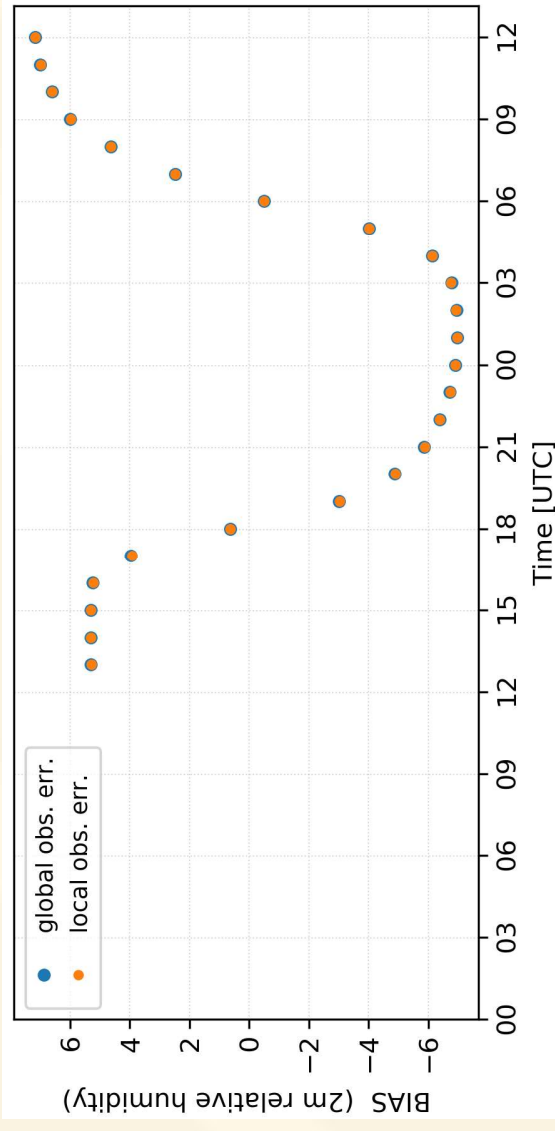
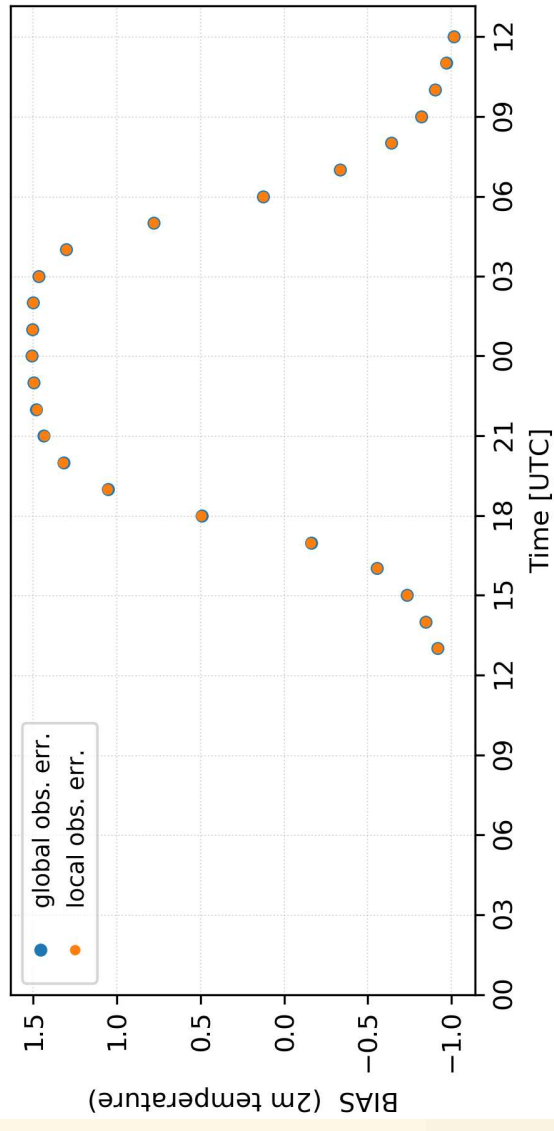
Comparison of T_{2m} & HU_{2m} with Austrian TAWES stations

- Bias & RMSE improve for some stations ...
- ... but in average almost no impact

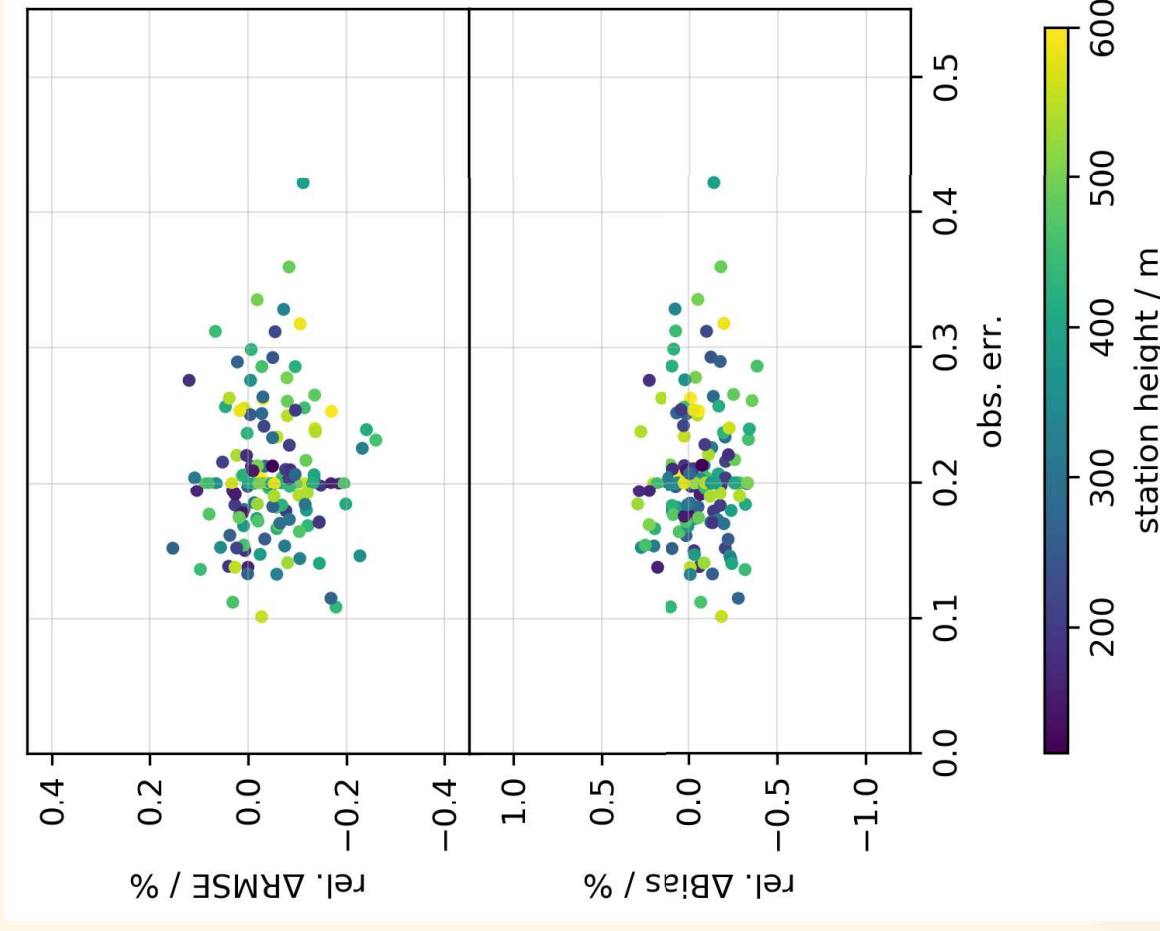


Comparison of T_{2m} & HU_{2m} with Austrian TAWES stations

- Bias & RMSE improve for some stations ...
- ... but in average almost no impact

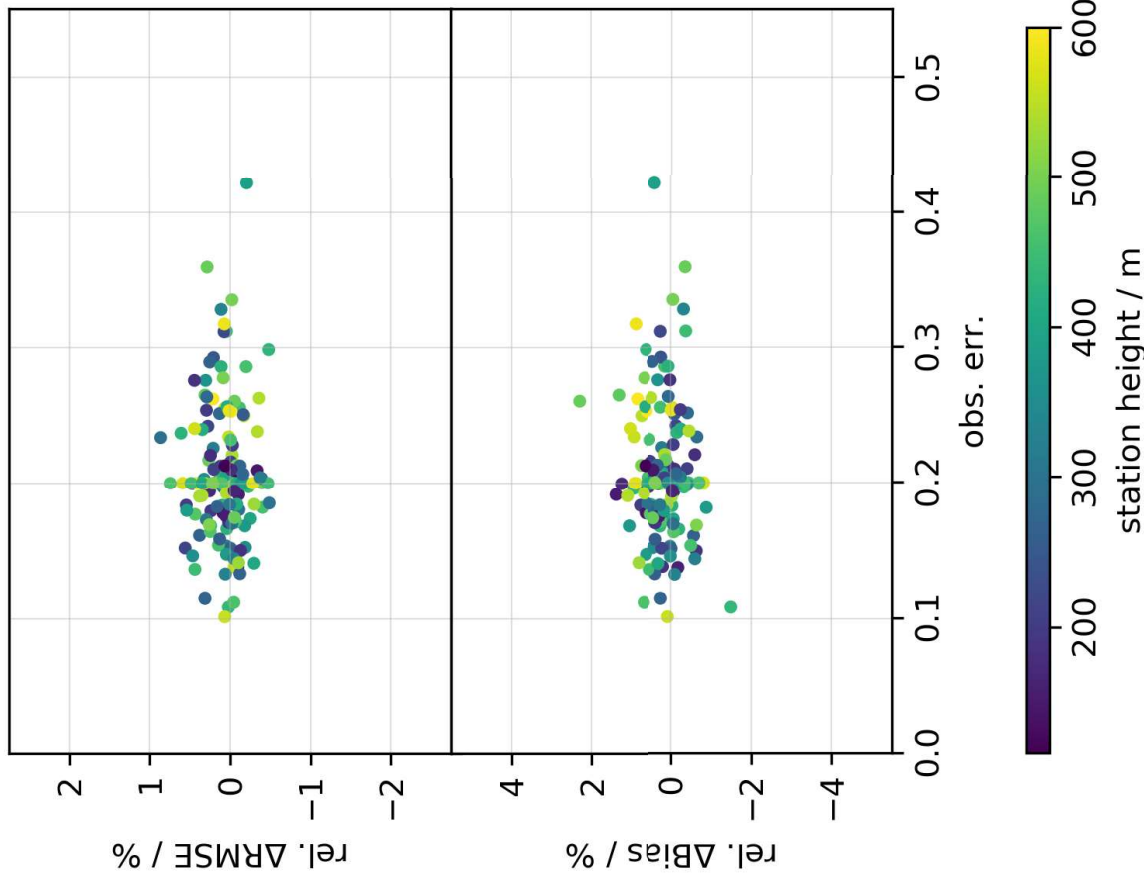


Comparison of T_{2m} & HU_{2m} with Austrian TAWES stations



- Slight degradation for T_{2m}

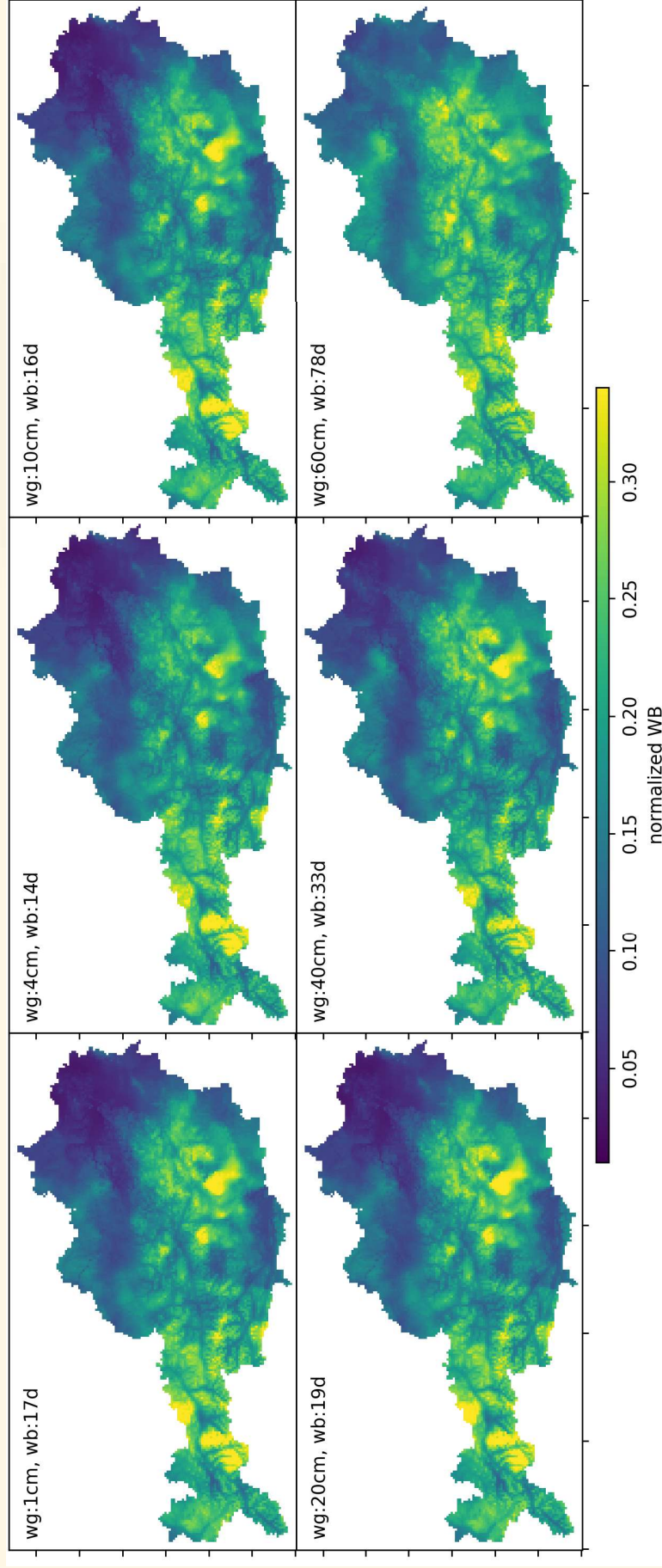
Comparison of T_{2m} & HU_{2m} with Austrian TAWES stations



- Slight degradation for T_{2m}
- Slight improvement for HU_{2m}
- No correlation with error magnitude or station height

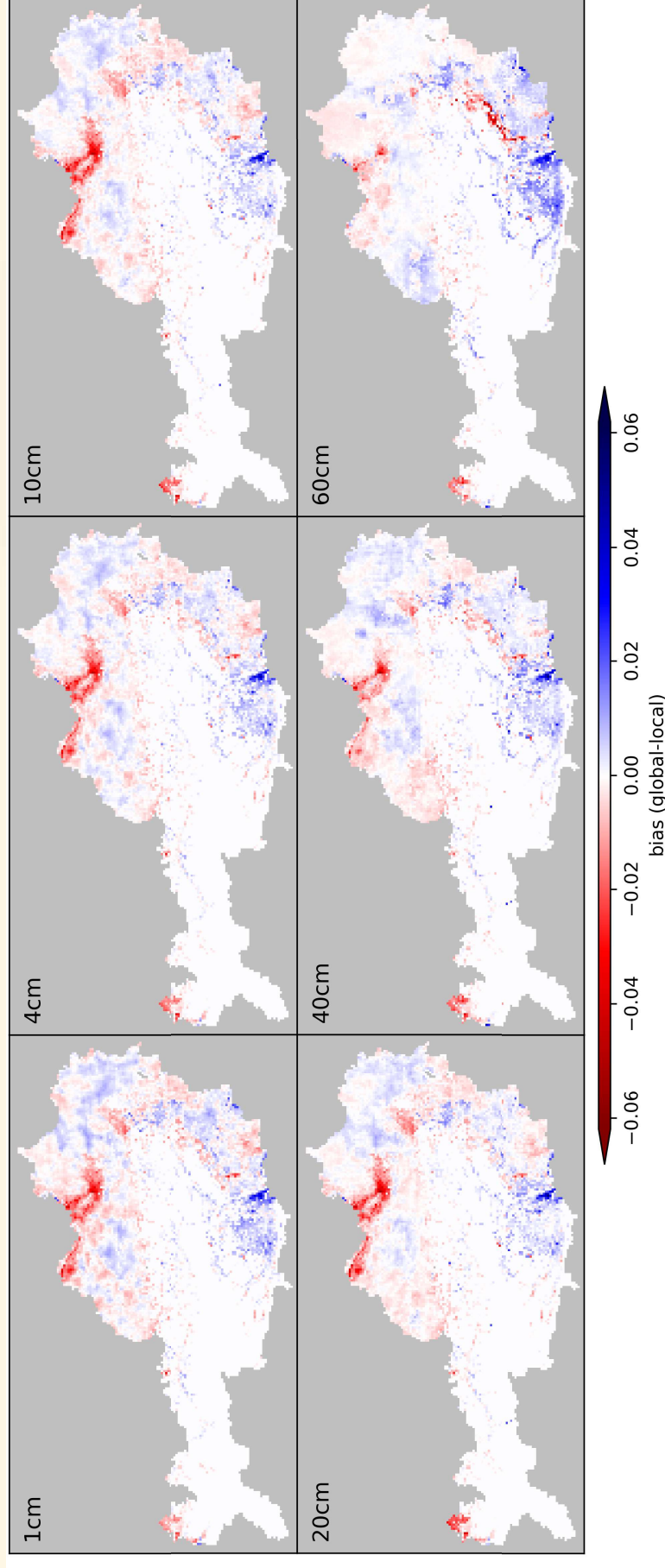
Water balance

- $WB = RR - ET$
- ET computed from temperature (*Haslinger et al. 2016*)



Water balance

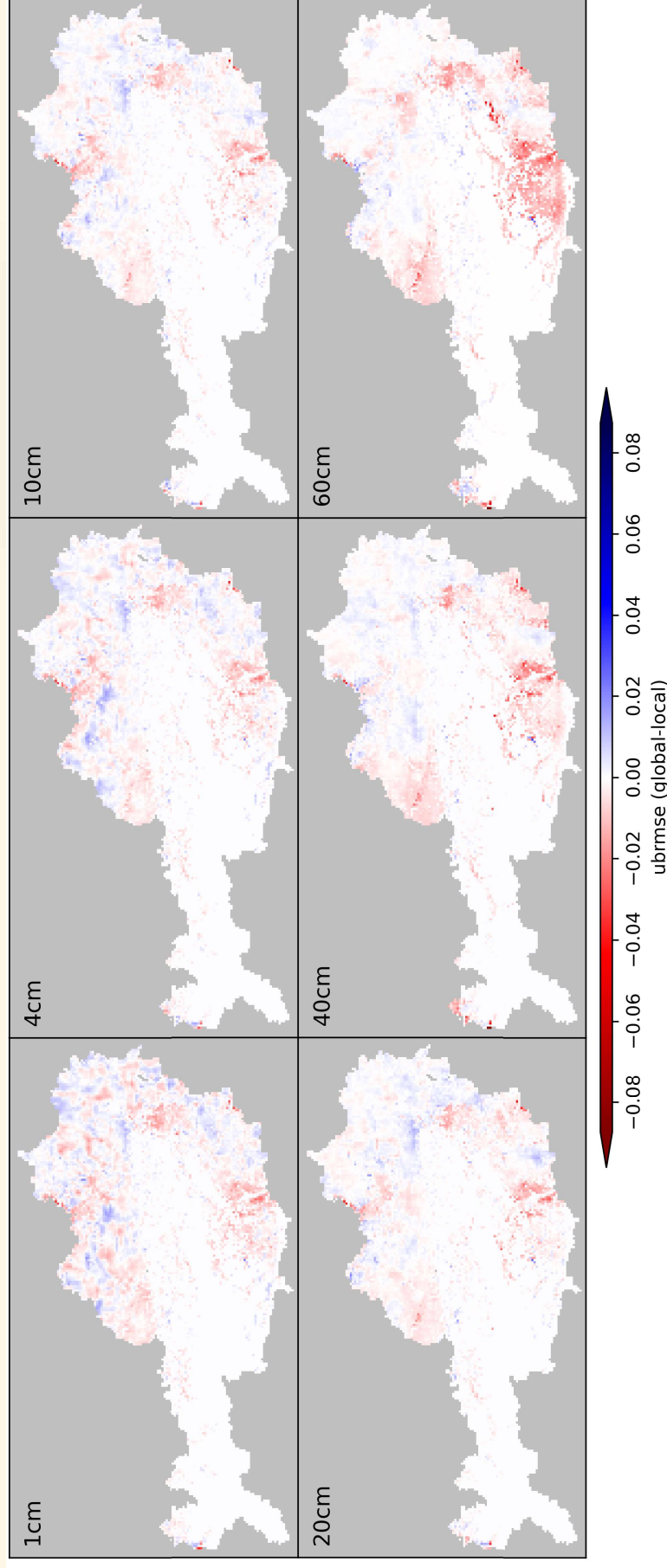
- $WB = RR - ET$
- ET computed from temperature (*Haslinger et al. 2016*)



- In average, almost no change for bias ...

Water balance

- $WB = RR - ET$
- ET computed from temperature (*Haslinger et al. 2016*)



- In average, almost no change for bias ...
- ... and ubRMSE with local observation errors

Summary & Outlook

- Assimilation of SCATSAR-SWI with SURFEX
- Observation error obtained from Triple Collocation Analysis
 - ▷ NWP: – small impact on T_{2m} & HU_{2m}
 - in average none
 - ▷ Water balance: – visible impact on soil moisture computation
 - in average no benefit

Summary & Outlook

- Assimilation of SCATSAR-SWI with SURFEX
- Observation error obtained from Triple Collocation Analysis
 - ▷ NWP: – small impact on T_{2m} & HU_{2m}
 - in average none
 - ▷ Water balance: – visible impact on soil moisture computation
 - in average no benefit
 - ▷ 1.25 km resolution in preparation
 - ▷ Run computations on European domain