#### Data assimilation in 3D-VAR ALADIN-CZ: data thinning and error-inflation for aircraft & satellites.

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Observation error diagnostic

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- Data thinning
- Error inflation
- Forecast impact

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- Data thinning
- Error inflation
- Forecast impact

#### Conclusion

- Aladin/CZ:  $\delta x = 4.7$  km (status presentation)
- BlendVar = DFI Blending + 3D-Var (since 2015)

$$J(\vec{x}) = \frac{1}{2} (\vec{x_b} - \vec{x})^T \mathbf{B}^{-1} (\vec{x_b} - \vec{x}) + \frac{1}{2} (\vec{y} - H(\vec{x}))^T \mathbf{R}^{-1} (\vec{y} - H(\vec{x})).$$
(1)

R is observation error covariance matrix:

- diagonal:  $\sigma_o^2 = var(\vec{\epsilon_o})$
- non-diagonal:  $cov[\vec{\epsilon_o}(\vec{\epsilon_o})^T] \rightarrow error correlations$

#### **R** assumption

• Error correlations are neglected.

• using Desroziers et al. (2005) to approximate:

$$cov[\vec{d_a^o}(\vec{d_b^o})^T] \approx \tilde{\mathbf{R}}$$
 (2)

$$\begin{split} d^o_a &= (\vec{y} - \mathbf{H}[\vec{x_a}]) \text{ (analysis departure)} \\ d^o_b &= (\vec{y} - \mathbf{H}[\vec{x_b}]) \text{ (background departure)} \end{split}$$

#### Assumptions:

• 
$$E[\vec{\epsilon_b}] = E[\vec{\epsilon_o}] = E[\vec{\epsilon_b}(\vec{\epsilon_o})^T] = E[\vec{\epsilon_o}(\vec{\epsilon_b})^T] = 0$$

different correlation length-scales btw background and observation errors

#### Simplifications:

can be apply iteratively – good convergence (using one-iteration)



#### Reduction of error correlations:

- data thinning: reduction observation density so that correlations are not relevant
- error inflation: use diagonal **R** with larger  $\sigma_o$  than diagnostic suggest

#### How to set:

- Data thinning:
  - estimate spatial error correlations by Desroziers
  - 2 optimal thinning distance: error correlations  $\leq$  0.15 0.2 [3]

#### Error inflation:

- **(**) estimate observation error by Desroziers  $\sigma_o^{der}$
- 2 artificial inflation of  $\sigma_o^{der}$  to reduce error-correlations (spatial, inter-channels,...)
- the error inflation is changed through sigma\_coeff (SC)



# Aircraft observation

- the Mode-S MRAR data (CZ domain)
- observation pairs  $d_a^o$  and  $d_b^o$ :
  - 2015-07-05/07-30 (summer) 2016-02-25/03-25 (winter)
  - less than 1 hour apart
  - separately for each aircraft type
  - horizontal error correlations:
    - data at specific levels  $\pm$ 2-hPa btw 150-400 hPa (Fig)
    - separation distance 10-km
  - vertical error correlations:
    - data from 400-950 hPa
    - separation distance 4-hPa



## Horizontal error correlations

• Optimal horizontal thinning btw. 25 – 35 km ( $ho \sim$  0.2) [3]



Figure : Estimates of horizontal error correlations based on Desroziers (top) and the number of a collocations (bottom) as a function of separation distance for MRAR.

## Horizontal error correlations

• The 3h-forecast impact of data thinning: 5, 25, 50 and 100 km



Figure : The relative change of RMSE for 3h-forecast wrt MRAR.



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# Vertical error correlations

• Optimal vertical thinning  $\sim$  20 hPa ( $ho \sim$  0.2) [3]



Figure : Estimates of vertical error correlations based on Desroziers (top) and the number of a collocations (bottom) as a function of separation distance for MRAR.

## Vertical error correlations

#### • The 3h-forecast impact of vertical thinning: 18 hPa



Figure : The relative change of RMSE for 3h-forecast wrt MRAR.



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# Observation error inflation I

• Observation errors by Desroziers for MRAR/AMDAR



Figure : Observation error estimation for the AMDAR (red) and MRAR (blue) measurements based on Desroziers (solid) and the predefined error in the ALADIN-CZ (dotted). Scores from the period 01 Jul - 30 Sep 2015.

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## Observation error inflation II

- Desroziers: SC ~ 0.6
- Aladin/CZ: SC ~ 0.7
- Optimal: ?





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## Observation error inflation II

- Desroziers: SC ~ 0.6
- Aladin/CZ: *SC* ~ 0.7
- Optimal:  $SC \sim 2.0$





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# Forecast Impact of NEW changes

	REF	NEW	
H-Thin	50 km	25 km	
V-Thin	—	18 hPa	
SC	0.7	2.0	

- 20 days (Feb-Mar/2016)
- production at 6, 12 UTC
- RMSE scores wrt TEMP
- opsitive/negative



- new thinning (25 km, 18 hPa) for MRAR (AMDAR) in Aladin/CZ
- similar observation errors btw MRAR and AMDAR: the same error-inflation (2.0)
- applicability of the Desroziers diagnostic for estimating observation error is questionable:
  - inconsistency btw error inflation estimated by Desroziers (  $\sim$  0.6) and based on forecast study (  $\sim$  2.0)
- should be more studied:
  - a violence of the method assumptions
  - isotropic and homogeneous B-matrix
  - ???

## Horizontal error correlations

 The MRAR/AMDAR data reduction using 5-, 25-, 50- and 100-km horizontal thinning





#### • The MRAR/AMDAR data reduction using 18-hPa vertical thinning





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Data assimilation in 3D-VAR ALADIN-CZ

- observation error: correlations and inflation
- AMSU-A/MHS/SEVIRI on board NOAA-18,19, MetOp-A and Meteosat-10
- observation pairs  $d_a^o$  and  $d_b^o$ :
  - 2016-01-01/01-20
  - less than 1 hour apart
  - separately for each instrument and satellite
  - 20-km separation distance ( $\pm$ 10 km)



# Spatial error correlations: AMSU-A



Figure : Estimates of spatial-error correlations as a function of separation distance for AMSU-A channels. Optimal thinning corresponds to AMSU-A horizontal resolution (in nadir)  $\sim$  50 km [3].

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## Spatial error correlations: MHS



Figure : Estimates of spatial-error correlations as a function of separation distance for MHS channels. Optimal thinning corresponds to  $\sim 70 - 90$  km [3].

# Spatial error correlations: SEVIRI



Figure : Estimates of spatial-error correlations as a function of separation distance for SEVIRI. Data are pre-thinned (every 5th pixel) in bator. Optimal thinning corresponds to  $\sim 20$  km [2]

# Inter-channel error correlations: AMSU-A/MHS/SEVIRI



Figure : Estimates of interchannel error correlations for AMSU-A/MHS/SEVIRI (from the left) channels based on Desroziers diagnostic. The matrices have been made symetric by using  $R = \frac{1}{2}(R + R^T)$ .



## The AMSU-A error estimation



Figure : The observation error estimations by Desroziers (black), predefined in Aladin/CZ (green) and the instrument error NEdT (OSCAR-WMO) (red) of AMSU-A.



## The MHS error estimation



Figure : The observation error estimations by Desroziers (black), predefined in Aladin/CZ (green) and the instrument error NEdT (OSCAR-WMO) (red) of MHS.



## The SEVIRI error estimation



Figure : The observation error estimations by Desroziers (black), predefined in Aladin/CZ (green) and the instrument error NEdT (OSCAR-WMO) (red) of SEVIRI.



#### • finding optimal SC based on impact studies:

- evaluation of the 6h-fcst impact on STD of  $d_b^o$
- no blending, 10-days (03/2016) at 0, 6, 12 and 18 UTC
- wrt temp/amdar/sats (not shown)

Instrument	Thin-Old	Thin-New	SC.Ald	SC.Des	SC.Optimal
AMSU-A	70 km	50 km	1	$\sim 0.8$	$\sim 0.81, 2, 3$
MHS	70 km	70 km	1	$\sim 0.3$	$\sim 0.4, 0.6, \frac{0.8}{.1.2}$
SEVIRI	70 km	20 km	1	$\sim 0.3$	$\sim 0.5, 0.7, {\color{red} 0.9}$



## The 6h-forecast impact of NEW changes

- positive impact on humidity bias/stdv (3 4%)
- negative impact on T700hPa bias ( $\sim 1\%$ )



#### Overall satellite impact on 6h-forecast

• noBlending (conv, Sconv): RH bias/stdv (+4%); T700 bias (-1%)





## Overall satellite impact on 6h-forecast

- noBlending (conv, Sconv): RH bias/stdv (+4%); T700 bias (-1%)
- Blending (Bconv, BSconv): consistent, but the impact reduction





- new data thinning and observation error inflation for AMSU-A/MHS/SEVIRI
- two ways of propagating satellites observations to our analysis:
  - DFI blending with ARPEGE
  - 3D-Var in Aladin/CZ
- blending provides sufficient information about long-scales captured by AMSU-A/MHS
- $\bullet\,$  satellite DA in 3D-Var Aladin/CZ adds slight (RMSE  $\sim$  1%) improvement on the top of blending
- How beat the Blending in terms of this study:
  - high-resolution observations (IASI, radar,...)
  - using as much data as possible (full  ${\bm R}$  matrix) to resolve small-scales



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#### Thank you for your attention.

